

Saksham Gupta

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Summary

*Electrical & Computer Engineering student with hands-on experience in **BMS, Power Converters, and STM32 embedded systems**. Strong in project leadership, cross-functional teamwork, and designing solutions showcased in international competitions.*

Skills

- **Electrical Systems:** BMS, Inverter, Switchgear, Harnessing
- **PCB & Circuit Design:** KiCad, Altium, Eagle (2+ yrs)
- **Embedded Systems:** ESP32, Raspberry PI Pico, STM32, Arduino, Raspberry Pi
- **Hardware Expertise:** Micro/HV soldering, Power Systems, HVAC Systems
- **Software Expertise:** AutoCAD, COMSOL, Java, C/C++, Python, PHP, MySQL

Experience

Delta Zero

Electronics Design Engineer

NOV, 24 – JAN, 25

- Designed and developed the electronic control hardware for a custom 3D printer system
- Prototyped, assembled, and tested the electronics to validate system performance

Team Vegapod Hyperloop | EHW'24

Electrical Head

AUG, 23 – JUL, 24

- Designed a Custom Scalable Battery Pack including a BMS reducing the cost by 50%.
- Designed a Levitation Controller for powering the EMS Units and **successfully achieved 1DoF Levitation**.
- Represented Team Vegapod Hyperloop at the European Hyperloop Week competition in Zürich, Switzerland.

Team Vegapod Hyperloop | EHW'23

Electrical Engineer

AUG, 22 – JUL, 23

- Developed a **3-phase SPWM inverter** to power a custom Linear Induction Motor.
- Assembled and tested a complete power system, ensuring functionality and reliability.
- Represented Team Vegapod Hyperloop at the European Hyperloop Week competition in Scotland.

Education

- **B.Tech in Electrical & Computer Engineering** – MIT WPU | GPA: 7.13 (Aug 2022 – July 2026)
- **Class 12 (CBSE)** – Rukmini Devi Public School, New Delhi | 90% (2022)
- **Class 10 (CBSE)** – Rukmini Devi Public School, New Delhi | 88% (2020)

Hardware Projects

- **3 Phase Inverter**
 - Developed a SPWM inverter using IGBTs for induction motor control. Controlled using a dedicated VCU with CAN protocol.
- **Power Electronic Constant Current Controller**
 - Developed a Constant Current Controller for Powering Inductive Loads with set value received using UART.
- **Scalable Battery Module**
 - Designed a modular li-po battery pack with BMS integration for High Voltage Systems in EVs.
- **2 Degree of Freedom; Pick and Place Robot**
 - Designed a Pick and Place robot with an Electromagnetic Gripper and Live Visualization and Control on an ElectronJs Application with serial communication.
- **Quadcopter (MultiWii)**
 - Built a quadcopter with the MultiWii firmware running on an Arduino and a custom wireless transceiver utilising NRF24L01 modules.

Software Projects

- **File Sharing Application:** Android Native (Java) and WPF (C#)
- **Multi-Threaded Downloader:** Built using JS
- **Automatic Backup Application:** Built using C# (WPF Application)
- **Password Manager Application:** Android Native, NextJS